

General Description

The GUM-4538-MTRUSB150 module series is a family of stand alone GPS receivers featuring the high performance MediaTek MT3337 positioning engine. These flexible and cost effective receivers offer numerous connectivity options in a miniature 45x38x13.8mm package. Their compact architecture and power and memory options make GUM-4538-MTRUSB150 modules ideal for battery operated mobile devices with very strict cost and space constraints.

The 56-channel MediaTek MT3337 positioning engine boasts a Time-To-First-Fix (TTFF) of under 1 second. The dedicated acquisition engine, with over 1 million correlators is capable of massive parallel time/frequency space searches, enabling it to find satellites instantly. Innovative design and technology suppresses jamming sources and mitigates multipath effects, giving GUM-4538-MTRUSB150 GPS receivers excellent navigation performance even in the most challenging environments.

Applications

- LBS (Location Based Service)
- PND (Portable Navigation Device)
- Vehicle navigation system
- Mobile phone



**Figure : GUM-4538-MTRUSB150
Top View**

Features

- Build on high performance, low-power MediaTek MT3337 chip set
- Ultra high sensitivity: -165dBm
- Extremely fast TTFF at low signal level
- Built in high gain LNA
- Low power consumption: Max 45mA@3.3V
- NMEA-0183 compliant protocol or custom protocol
- Operating voltage: 3.0V--5.0V
- Operating temperature range: -40to85 °C
- Patch Antenna Size: 25x25x4mm
- Module Size: 45x38x13.8mm
- Communication type: USB
- Baud rate: 9600bps
- Wire interface type: USB (type A) male head , L=150cm
- RoHS compliant (Lead-free)

1 Description

1.1. Key Features

Parameter	Specification
Power Supply	<ul style="list-style-type: none"> Supply voltage: 3.0V~5.0V Typical: 3.3V
Power Consumption	<ul style="list-style-type: none"> Acquisition: 45mA @VCC=VBAT=3.3V Tracking: 25mA @VCC=VBAT=3.3V Backup: 15uA @VBAT=3.3V
Receiver Type	<ul style="list-style-type: none"> Code 56 search channels ,22 synchronous tracking channels GPS&QZSS L1 1575.42MHz C/A ,GLONASS L1OF 1602MHz, SBAS: WAAS, EGNOS, MSAS, GAGAN
Sensitivity	<ul style="list-style-type: none"> Tracking: -165dBm Re-acquisition: -156dBm Acquisition: -146dBm
TTF (Autonomous)	<ul style="list-style-type: none"> Cold start: 35s typ @-130dBm Warm start: 30s typ @-130dBm Hot start: 1s typ @-130dBm
Horizontal Position Accuracy (Autonomous)	<ul style="list-style-type: none"> <2.5m CEP @-130 dBm
Max Update Rate	<ul style="list-style-type: none"> Up to 10Hz,1Hz by fault
Accuracy of 1PPS Signal	<ul style="list-style-type: none"> not enabled
Acceleration Accuracy	<ul style="list-style-type: none"> Without aid: 0.1m/s²
Dynamic Performance	<ul style="list-style-type: none"> Maximum altitude: 18,000m Maximum velocity: 515m/s Acceleration: 4G
UART Port	<ul style="list-style-type: none"> UART Port: USB_DM and USB_DP Supports baud rate from 4800bps to 115200bps, 4800bps by default USB port for NMEA and MTK output, binary or MTK proper Agreement input
Temperature Range	<ul style="list-style-type: none"> Normal operation: -40°C ~ +85°C Storage temperature: -45°C ~ +125°C
Physical Characteristics	<ul style="list-style-type: none"> Size: 45±0.50 × 38±0.50 ×13.8±0.50mm Wire interface type: USB (type A) male head , L=150cm Weight: Approx. 35g

1.2 Power Supply

Regulated power for the GUM-4538-MTRUSB150 is required. The VCC Pin Need a stable DC voltage supply. Power supply ripple must be less than 30mV. The input voltage Vcc should be 3.0V~5.0V, Recommended power supply voltage is 3.3V . maximum current is 35mA. Suitable decoupling must be provided by external decoupling circuitry.

1.3 USB Ports:

GUM-4538UB8FUSB300 Modules provide a USB version 2.0 FS (Full Speed, 12Mbit/s) interface as an alternative to the UART. The pull-up resistor on USB_DP is integrated to signal a full-speed device to the host. Provides a Microsoft ® certified USB driver for Windows XP and Windows Vista operating systems. Windows 7/8/10 will also be supported following certification.

Operating System	Support level
Windows XP	Certified
Windows Vista	Certified
Windows 7/8/10	Certified

2 Application

The module is equipped with a 5-pin pad that connects to your application platform. The GUM-4538-MTRUSB150 module It consists of a MediaTek MT3337 single chip GNSS IC which includes the RF part and Baseband part, a patch antenna, a LNA, a SAW filter, a TCXO, a crystal oscillator, Also comes with a 0.22F crystal capacitor ,can backup satellite ephemeris about 2 hour.

2.1. Pin Assignment

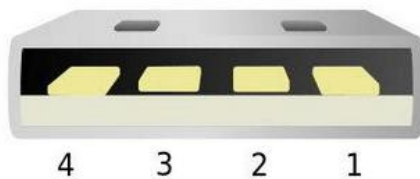


Figure 2: Pin Assignmen

CON Pin Description

Pin No.	Pin name	I/O	Description	Remark
1	VCC	I	Module Power Supply	
2	USB_DM	I/O	USB Data (D-)	
3	USB_DP	I/O	USB Data (D+)	
4	GND	G	Ground	

2.2 Mechanical Dimensions

This chapter describes the mechanical dimensions of the GUM-4538-MTRUSB150 module. Size unit (mm)

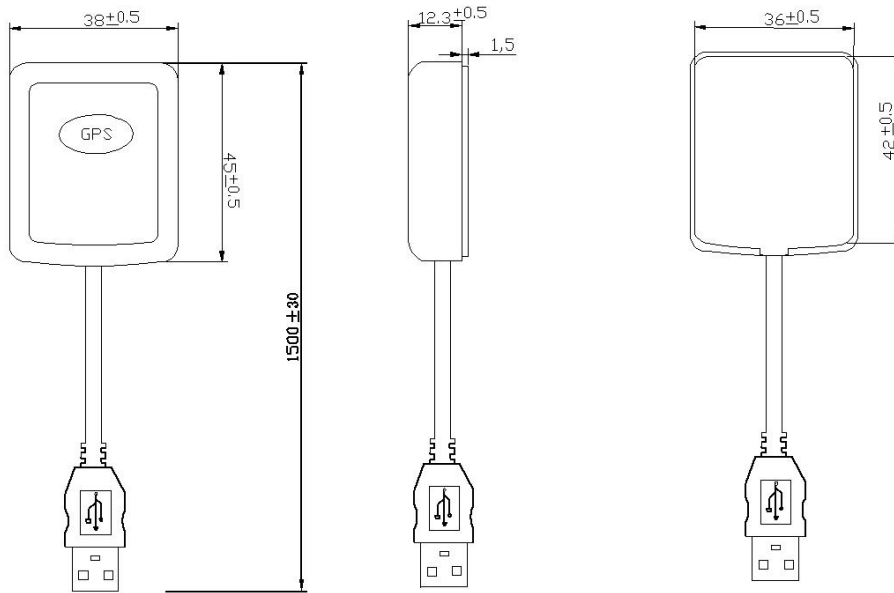


Figure 3:GUM-4538-MTRUSB150 Specification size chart

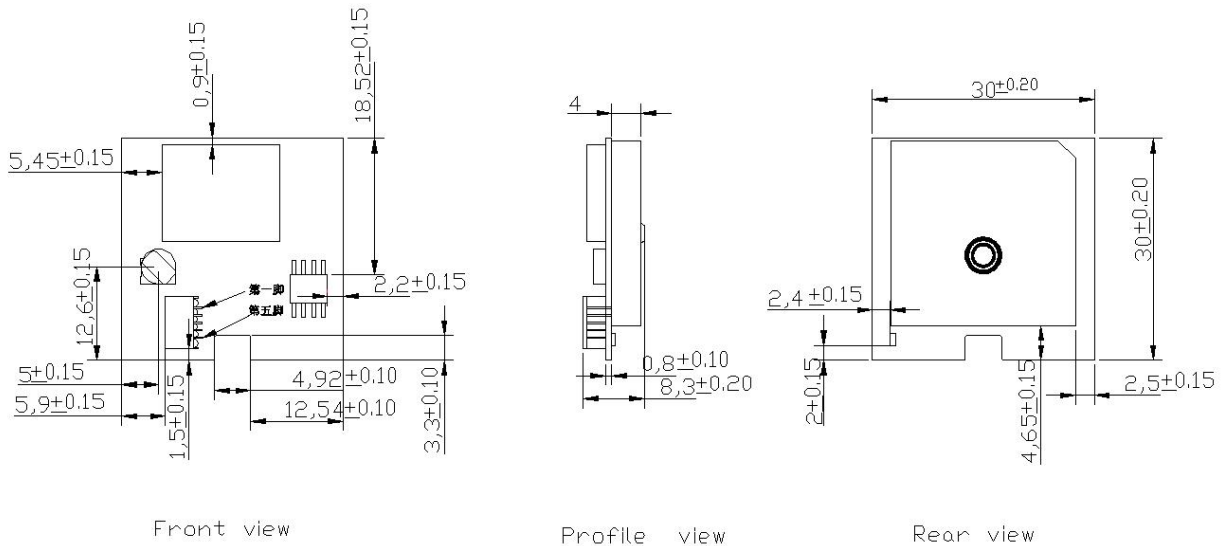


Figure 4: Specification size chart

3 NMEA 0183 Protocol

The NMEA protocol is an ASCII-based protocol, Records start with a \$ and with carriage return/line feed. GPS specific messages all start with \$GPxxx is a three-letter identifier of the message data that follows. NMEA messages have a check sum, which allows detection of corrupted data transfers.

The Gotop GUM-4538-MTBDUSB150 Initialization location mode for GPS dual mode.

Output data: \$GPGGA, \$GPGLL,\$GPGSA,\$GPGSV, \$GPRMC and \$GPVTG.

Table 1: NMEA-0183 Output Messages

NMEA Record	DESCRIPTION
GGA	Global positioning system fixed data
GLL	Geographic position—latitude/longitude
GSA	GNSS DOP and active satellites
GSV	GNSS satellites in view
RMC	Recommended minimum specific GNSS data
VTG	Course over ground and ground speed

3.1 GGA-Global Positioning System Fixed Data

\$GPGGA, 161229.487,3723.24751,N, 12158.34160,W, 1,07,1.0,9.0,M.0000*18

Table 2: GGA Data Format

Name	Example	Units	Description
Message ID	\$GPGGA		GGA protocol header
UTC Position	161229.487		hhmmss.sss
Latitude	3723.2457		ddmm.mmmm
N/S indicator	N		N=north or S=south
Longitude	12158.3416		dddmm.mmmm
E/W Indicator	W		E=east or W=west
Position Fix Indicator	1		See Table 2-1
Satellites Used	07		Range 0 to 12
HDOP	1.0		Horizontal Dilution of Precision
MSL Altitude	9.0	meters	
Units	M	meters	
Geoids Separation		meters	

Units	M	meters	
Age of Diff.Corr.		second	Null fields when DGPS is not Used
Diff.Ref.Station ID	0000		
Check sum	*18		
<CR> <LF>			End of message termination

Table 2-1: Position Fix Indicators

Value	Description
0	Fix not available or invalid
1	GPS SPS Mode, fix valid
2	Differential GPS, SPS Mode, fix valid
3	GPS PPS Mode, fix valid

3.2 GLL-Geographic Position – Latitude/Longitude

\$GPGLL , 3723.24755, N,12158.34161, W,161229.487, A*2C.

Table 3: GLL Data Format

Name	Example	Units	Description
Message ID	\$GPGLL		GLL protocol header
Latitude	3723.2475		ddmm.mmmm
N/S Indicator	N		N=north or S=south
Longitude	12158.3416		dddmm.mmmm
E/W Indicator	W		E=east or W=west
UTC Position	161229.487		hhmmss.sss
Status	A		A=data valid or V=data not valid
Check sum	*2C		
<CR> <LF>			End of message termination

3.3 GSA-GNSS DOP and Active Satellites

\$GPGSA , A, 3, 07, 02, 26,27, 09, 04,15, , , , , 1.8,1.0,1.5*33.

Table 4: GSA Data Format

Name	Example	Units	Description
Message	\$GPGSA		GSA protocol header

Mode 1	A		See Table 4-2
Mode 2	3		See Table 4-1
Satellite Used	07		Sv on Channel 1
Satellite Used	02		Sv on Channel 2
...
Satellite Used			Sv on Channel 12
PDOP	1.8		Position Dilution of Precision
HDOP	1.0		Horizontal Dilution of Precision
VDOP	1.5		Vertical Dilution of Precision
Check sum	*33		
<CR> <LF>			End of message termination

Table3-1: Mode 1

Value	Description
1	Fix not available
2	2D
3	3D

Table 3-2: Mode 2

Value	Description
M	Manual-forced to operate in 2D or 3D mode
A	Automatic-allowed to automatically switch 2D/3D

3.4 GSV-GPS Satellites in View

\$GPGSV , 2, 1, 07, 07, 79,048, 42, 02, 51,062, 43, 26, 36,256, 42, 27, 27, 138,42*71

\$GPGSV, 2, 2, 07, 09, 23,313, 42, 04, 19, 159, 41, 15,12,041, 42*41.

Table 5: GGA Data Format

Name	Example	Units	Description
Message ID	\$GPGSV		GSV protocol header
Number of Message	2		Range 1 to 3
Message Number	1		Range 1 to 3
Satellites in View	07		

Satellite ID	07		Channel 1(Range 1 to 32)
Elevation	79	degrees	Channel 1(Maximum 90)
Azinmuth	048	degrees	Channel 1(True, Range 0 to 359)
SNR(C/NO)	42	dB/Hz	Range 0 to 99,null when not tracking
...			...
Satellite ID	27		Channel 4(Range 1 to 32)
Elevation	27	degrees	Channel 4(Maximum 90)
Azimuth	138	degrees	Channel 4(True, Range 0 to 359)
SNR(C/NO)	42	dB/Hz	Range 0 to 99, null when not tracking
Check sum	*71		
<CR> <LF>			End of message termination

Depending on the number of satellites tracked multiple messages of GSV data may be required.

3.5 RMC-Recommended Minimum Specific GNSS Data

\$GPRMC, 161229.487, A, 3723.24751, N, 12158.34161, W, 0.13,309.62, 120598,, *10

Table 6: RMC Data Format

Name	Example	Units	Description
Message ID	\$GPRMC		RMC protocol header
UTC Position	161229.487		hhmmss.sss
Status	A		A=data valid or V=data not valid
Latitude	3723.24751		ddmm.mmmmm
N/S Indicator	N		N=north or S=south
Longitude	12158.34161		dddmm.mmmmm
E/W Indicator	W		E=east or W=west
Speed Over Ground	0.13	Knots	
Course Over	309.62	Degrees	True
Ground			
Date	120598		dummy
Magnetic variation		Degrees	E=east or W=west
Check sum	*10		
<CR> <LF>			End of message termination

3.6 VTG-Course Over Ground and Ground Speed

\$GPVTG, 309.62, T, M, 0.13, N, 0.2, K*6E

Table 7: VTG Data Format

Name	Example	Units	Description
Message ID	\$GPVTG		VTG protocol header
Course	309.62	Degrees	Measured heading
Reference	T		True
Course		Degrees	Measured heading
Reference	M		Magnetic
Speed	0.13	Knots	Measured horizontal speed
Units	N		Knots
Speed	0.2	Km/hr	Measured horizontal speed
Units	K		Kilometer per hour
Check sum	*6E		
<CR> <LF>			End of message termination

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